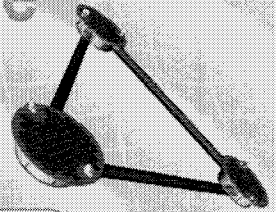


# LISA Instrument Performance

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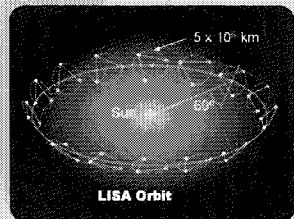


## Abstract

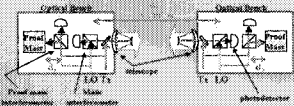
LISA is designed to observe gravitational waves in the frequency band from  $10^{-2}$  to  $10^{-4}$  Hz, where a rich spectrum of sources is expected. The measurements must be made from space to avoid the large motions of the earth that prevent the current generation of detectors (e.g. LIGO) from operating at these frequencies. The technology and expected performance behind this measurement capability will be reviewed with an emphasis on the interferometric measurement system, including recent laboratory results showing a novel tunable frequency-stabilized laser.

## Overview of the Mission

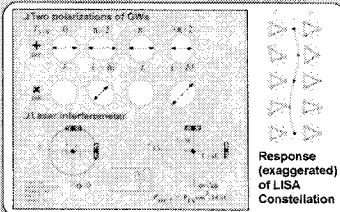
The LISA mission studies gravitational waves by detecting the strain they produce with a laser interferometer that measures the distance between pairs of freely floating proof masses arranged in a  $5 \times 10^6$  km equilateral triangle constellation that orbits the sun  $20^\circ$  behind Earth's orbit. The plane of the triangle is angled at  $60^\circ$  with respect to the ecliptic. Each of the three spacecraft are in independent orbit around the sun, so no station-keeping is required to keep the constellation together. The proof masses are isolated from disturbances by using drag-free satellite technology that keeps a spacecraft centered around the proof mass as it moves.



The LISA interferometer is placed in a heliocentric orbit at 1 AU.



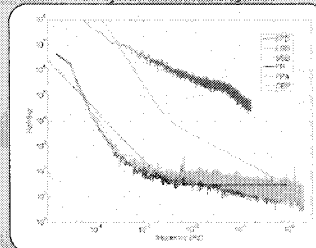
LISA uses a 3-way distance measurement to monitor the distance between proof masses on each SC.  
Short arm of  $d_{ij}$  = long arm of  $d_{jk} = d_{ki}$



Direct GW detectors like LISA measure the changes in distance between the proof masses caused by passing GWs.

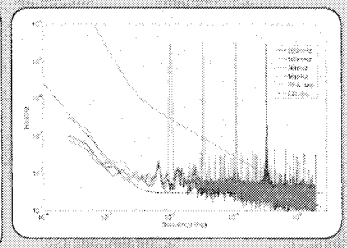
## Results: Same performance as without tunability

Stability of beat note between standard PDH system and sideband systems



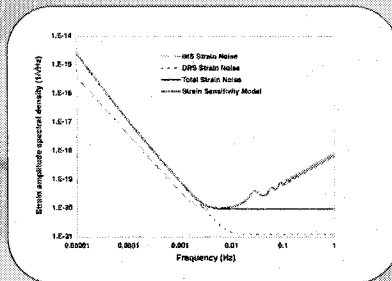
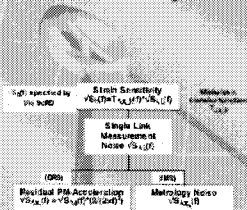
- All schemes work at ~ same level
- Performance matches current performance of standard system (not yet limited by sideband sensing)
- All schemes meet Current Baseline Requirement for pre-stab + arm-locking

Narrow-band modulation demonstration



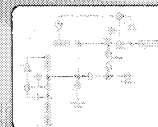
- Narrow-band modulation does not raise broad-band noise floor

## Noise Model/Requirements Flowdown

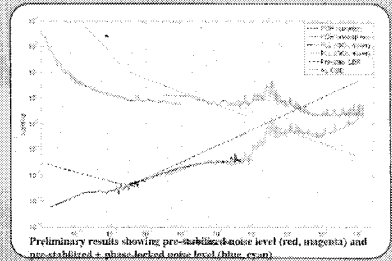


## Phase Locking with Pre-stabilization

- Demonstration of tunable pre-stabilization as an actuator in an external loop
- PLL has unity gain frequency (UGF) of ~10kHz
- PLL UGF limited by UGF of PDH loop, not actuator
- In-band noise meets Arm Locking CBE



Pre-stabilized phase lock loop



Preliminary results showing pre-stabilized noise level (red, magenta) and not-stabilized + phase-locked noise level (blue, cyan).

## Disturbance Reduction System (DRS) Interferometric Measurement System (IMS)

### High Level Error Budget

Disturbance	Transfer function to the arms	Transfer function to the detector
Proof mass acceleration	$\frac{1}{s^2}$	$\frac{1}{s^2}$
Scatterer acceleration	$\frac{1}{s^2}$	$\frac{1}{s^2}$
Scatterer position	$\frac{1}{s}$	$\frac{1}{s}$
Scatterer velocity	$\frac{1}{s}$	$\frac{1}{s}$
Scatterer acceleration	$\frac{1}{s^2}$	$\frac{1}{s^2}$
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